## APLISENS*

# USER MANUAL for meter with Pt100/500/1000 input 

## type:

## PMT-920

firmware version: 5.14 or higher


Read the user's manual carefully before starting to use the unit.
Producer reserves the right to implement changes without prior notice.
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## Explanation of symbols used in the manual:



- This symbol denotes especially important guidelines concerning the installation and operation of the device. Not complying with the guidelines denoted by this symbol may cause an accident, damage or equipment destruction.

IF THE DEVICE IS NOT USED ACCORDING TO THE MANUAL THE USER IS RESPONSIBLE FOR POSSIBLE DAMAGES.

(i)

- This symbol denotes especially important characteristics of the unit.

Read any information regarding this symbol carefully

## 1. BASIC REQUIREMENTS AND USER SAFETY


> - The manufacturer is not responsible for any damages caused by inappropriate installation, not maintaining the proper technical condition and using the unit against its destination.

- Installation should be conducted by qualified personnel . During installation all available safety requirements should be considered. The fitter is responsible for executing the installation according to this manual, local safety and EMC regulations.
- The unit must be properly set-up, according to the application. Incorrect configuration can cause defective operation, which can lead to unit damage or an accident.
- If in the case of a defect of unit operation there is a risk of a serious threat to the safety of people or property additional, independent systems and solutions to prevent such a threat must be used.
- The unit uses dangerous voltage that can cause a lethal accident. The unit must be switched off and disconnected from the power supply prior to starting installation of troubleshooting (in the case of malfunction).
- Neighbouring and mating equipment must meet the requirements of appropriate standards and regulations concerning safety and be equipped with adequate anti-overvoltage and anti-interference filters.
- Do not attempt to disassemble, repair or modify the unit yourself. The unit has no user serviceable parts. Units, in which a defect was stated must be disconnected and submitted for repairs at an authorized service centre.


[^0]- Do not use the unit in explosion hazard areas.
- Do not use the unit in areas with significant temperature variations, exposed to condensation or icing.
- Do not use the unit in areas exposed to direct sunlight.
- Make sure that the ambient temperature (e.g. inside the control box) does not exceed the recommended values. In such cases forced cooling of the unit must be considered (e.g. by using a ventilator).

The unit is designed for operation in an industrial environment and must not be used in a household environment or similar.

## 2. GENERAL CHARACTERISTICS

The PMT-920 meter is equipped with Pt 100/Pt 500/Pt 1000 type input, with automatic connection recognition ( three or four wire sensor). The measurement range spans from $-100{ }^{\circ} \mathrm{C}$ to $+600{ }^{\circ} \mathrm{C}$, and input is fully linearised accordingly to PN-EN60751+A2:1999 standard. Result is showed on 4-digit LED display.

The device can be equipped with one or two relay (or OC type) outputs. Device PMT920 is equipped with RS-485 / Modbus RTU communication interface and sensor supply output. The meter can be ordered in two power supply versions.

PMT-920 can be used for controlling and regulation of processes need proportional and threshold control like: temperature processes (heating or cooling), valves controlling or other.

## 3. TECHNICAL DATA

$$
\begin{aligned}
\text { relay: } & 0,1 \text { or } 2 \mathrm{NO}, 1 \mathrm{~A} / 250 \mathrm{~V} \text { AC }(\cos \varphi=1) \\
\text { or OC-type: } & 0,1 \text { or } 230 \mathrm{~mA} / 30 \mathrm{VDC} / 100 \mathrm{~mW} \\
\text { sensor power supply: } & 24 \mathrm{~V}+5 \%,-10 \% / \text { max. } 100 \mathrm{~mA} \text {, stabilized }
\end{aligned}
$$

Power supply voltage (depending on version)
External fuse (required)
Power consumption

Measurement input

Measurement range
Measurement accuracy
Measurement wires resistance
Outputs

Communication interface
85...230...260V AC/DC; $50 \div 60 \mathrm{~Hz}$
or 19...24...50V DC; 16...24... 35 V AC
T - type, max. 2 A
max. 4.5 VA @ $85 \div 260 \mathrm{~V}$ AC/DC
max. 4.5 VA @ $16 \mathrm{~V} \div 35 \mathrm{~V}$ AC
max. 4.5 W @ $19 \mathrm{~V} \div 50 \mathrm{~V}$ DC
Pt 100/ Pt 500/Pt 1000 type with automatic connection recognition ( 3 or 4-wires)
$-100^{\circ} \mathrm{C} \div+600^{\circ} \mathrm{C}$
$\pm 0,25 \% \pm$ one digit
max. $20 \Omega$ (every wire)

RS 485, 8N1 and 8N2, Modbus RTU, not separated

Baud rate
Display
(depending on version)
Data memory
Protection level

Housing type
Housing material
Housing dimensions
Mounting hole
Assembly depth
Panel thickness
Operating temperature
Storage temperature
Humidity
Altitude
Screws tightening max. torque
Max. connection leads diameter
Safety requirements

EMC
$1200 \mathrm{bit} / \mathrm{s} \div 115200 \mathrm{bit} / \mathrm{s}$
LED, 4 digit, 13 mm height, two-colour (red and green) or (for IP 65 version) 5 digit, 9 mm height, red
non-volatile memory, EEPROM type
IP 65 (from front, after using waterproof cover)
IP 40 (from front)
IP 20 (housing and connection clips)
panel
NORYL - GFN2S E1
$72 \times 36 \times 97 \mathrm{~mm}$
$66.5 \times 32.5 \mathrm{~mm}$
min. 102 mm
max. 5 mm
$0^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}$
$-10^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
5 to $90 \%$ no condensation
up to 2000 meters above sea level
0,5 Nm
2,5 mm ${ }^{2}$
according to: PN-EN 61010-1
installation category: II pollution degree: 2
voltage in relation to ground: 300 V AC
insulation resistance: >20M $\Omega$
insulation strength between power supply and input/output terminal: 1min. @ 2300V insulation strength between relays terminal: 1 min @ 1350V
according to: PN-EN 61326

This is a class $A$ unit. In housing or a similar area it can cause radio frequency interference. In such cases the user can be requested to use appropriate preventive measures.

## 4. DEVICE INSTALLATION

The unit has been designed and manufactured in a way assuring a high level of user safety and resistance to interference occurring in a typical industrial environment. In order to take full advantage of these characteristics installation of the unit must be conducted correctly and according to the local regulations.

- Read the basic safety requirements on page 3 prior to starting the installation.
- Ensure that the power supply network voltage corresponds to the nominal voltage stated on the unit's identification label.
- The load must correspond to the requirements listed in the technical data.
- All installation works must be conducted with a disconnected power supply.
- Protecting the power supply clamps against unauthorized persons must be taken into consideration.


### 4.1. UNPACKING

After removing the unit from the protective packaging, check for transportation damage. Any transportation damage must be immediately reported to the carrier. Also, write down the unit serial number on the housing and report the damage to the manufacturer.

Attached with the unit please find:

- user's manual,
- warranty,
- assembly brackets - 2 pieces.


### 4.2. ASSEMBLY



- The unit is designed for mounting indoor inside housings (control panel, switchboard) assuring appropriate protection against electric impulse waves. Metal housing must be connected to the grounding in a way complying with the governing regulations.
- Disconnect the power supply prior to starting assembly.
- Check the correctness of the performed connections prior to switching the unit on.

In order to assembly the unit, a $66.5 \times 32.5 \mathrm{~mm}$ mounting hole (Figure 4.1 ) must be prepared. The thickness of the material of which the panel is made must not exceed 5 mm . When preparing the mounting hole take the grooves for catches located on both sides of the housing into consideration (Figure 4.1). Place the unit in the mounting hole inserting it from the front side of the panel, and then fix it using the brackets (Figure 4.2). The minimum distances between assembly holes' axes - due to the thermal and mechanical conditions of operation - are $91 \mathrm{~mm} \times 57 \mathrm{~mm}$ (Figure 4.3).


Figure 4.1. Mounting hole dimensions


Figure 4.2. Installing of brackets, and dimensions of connectors.


Figure 4.3. Minimum distances when assembly of a number of units

### 4.3. CONNECTION METHOD

## Caution

- Installation should be conducted by qualified personnel . During installation all available safety requirements should be considered. The fitter is responsible for executing the installation according to this manual, local safety and EMC regulations.
- The unit is not equipped with an internal fuse or power supply circuit breaker.

Because of this an external time-delay cut-out fuse with minimal possible nominal current value must be used (recommended bipolar, max. 2A) and a power supply circuit-breaker located near the unit. In the case of using a monopolar fuse it must be mounted on the phase cable (L).

- The power supply network cable diameter must be selected in such a way that in the case of a short circuit of the cable from the side of the unit the cable shall be protected against destruction with an electrical installation fuse.
- Wiring must meet appropriate standards and local regulations and laws.
- In order to secure against accidental short circuit the connection cables must be terminated with appropriate insulated cable tips.
- Tighten the clamping screws. The recommended tightening torque is 0.5 Nm . Loose screws can cause fire or defective operation. Over tightening can lead to damaging the connections inside the units and breaking the thread.
- In the case of the unit being fitted with separable clamps they should be inserted into appropriate connectors in the unit, even if they are not used for any connections.
- Unused clamps (marked as n.c.) must not be used for connecting any connecting cables (e.g. as bridges), because this can cause damage to the equipment or electric shock.
- If the unit is equipped with housing, covers and sealing packing, protecting against water intrusion, pay special attention to their correct tightening or clamping. In the case of any doubt consider using additional preventive measures (covers, roofing, seals, etc.). Carelessly executed assembly can increase the risk of electric shock.
- After the installation is completed do not touch the unit's connections when it is switched on, because it carries the risk of electrical shock.

Due to possible significant interference in industrial installations appropriate measures assuring correct operation of the unit must be applied. To avoid the unit of improper indications keep recommendations listed below.

- Avoid common (parallel) leading of signal cables and transmission cables together with power supply cables and cables controlling induction loads (e.g. contactors). Such cables should cross at a right angle.
- Contactor coils and induction loads should be equipped with anti-interference protection systems, e.g. RC-type.
- Use of screened signal cables is recommended. Signal cable screens should be connected to the earthing only at one of the ends of the screened cable.
- In the case of magnetically induced interference the use of twisted couples of signal cables (so-called "spirals") is recommended. The spiral (best if shielded) must be used with RS-485 serial transmission connections.
- In the case of interference from the power supply side the use of appropriate antiinterference filters is recommended. Bear in mind that the connection between the filter and the unit should be as short as possible and the metal housing of the filter must be connected to the earthing with largest possible surface. The cables connected to the filter output must not run in parallel with cables with interference (e.g. circuits controlling relays or contactors).

Connections of power supply voltage and measurement signals are executed using the screw connections on the back of the unit's housing.


Figure 4.4. Method of cable insulation replacing and cable terminals


Figure 4.5. Terminals description (relay outputs)


Figure 4.6. Terminals description (OC-type outputs)

All connections must be made while power supply is disconnected !


Figure 4.7. Connection of power supply and relays
Contacts of relay outputs are not equipped with spark suppressors. While use the relay outputs for switching of inductive loads (coils, contactors, power relays, electromagnets, motors etc.) it is required to use additional suppression circuit (typically capacitor $47 \mathrm{nF} / \mathrm{min}$. 250VAC in series with 100R/5W resistor), connected in parallel to relay terminals or (better) directly on the load. In consequence of using the suppression circuit, the level of generated electromagnetic disturbances is lower, and the life of relay contacts rises.


Figure 4.8. Examples of suppression circuit connection:
a) to relay terminals; b) to the inductive load


Figure 4.9. Example of OC-type outputs connection
Temperature sensor can be connected to the device in typical 4-wire circuit (Figure 74.3a) or 3 -wire circuit (Figure 7b). Due to precision of measurement 4 -wire circuit is recommended.

(i)If 2 wire circuit is used it is recommended to connect sensor accordingly to Figure 7c. (4-wires circuit with shorted pins $6+7$ and $8+9$ ). In this case, the resistance of wires should be as small as possible, to avoid of measurement errors. Measured value can be corrected (constant correction) using „toFS" parameter from menu „inPt". Due to low precision 2-wire connection is not recommended.

When 4-wires or 2-wires connection is used, the resistance of particular wires ( $\mathrm{Ra} \div \mathrm{Rd}$ ) CAN BE DIFFERENT. When 3-wires connection is used, the resistance of particular wires (Ra $\div \mathrm{Rd}$ ) MUST BE IDENTICAL to enable proper compensation of it's resistance. The resistance of particular wire should not be greater than $20 \Omega$.
a)


$R b=R c=R d$


Rb , Rc can be different

Figure 7. Connection of sensors:
a) 4-wires circuit; b) 3-wires circuit; c) 2-wires circuit;

(i)The connection circuit should not be changed while unit is powered. Every change of connection while the unit is powered causes measurement errors by several seconds after change.

### 4.4. MAINTENANCE

The unit does not have any internal replaceable or adjustable components available to the user. Pay attention to the ambient temperature in the room where the unit is operating. Excessively high temperatures cause faster ageing of the internal components and shorten the fault-free time of unit operation.
In cases where the unit gets dirty do not clean with solvents. For cleaning use warm water with small amount of detergent or in the case of more significant contamination ethyl or isopropyl alcohol.

Using any other agents can cause permanent damage to the housing.

Product marked with this symbol should not be placed in municipal waste. Please check local regulations for disposal and electronic products.

## 5. FRONT PANEL DESCRIPTION



## Symbols and functions of push-buttons:

Symbol used in the manual: [ESC/MENU] Functions:

- Enter to main menu ( press and hold by at least 2 sec .)
- Exit the current level and Enter to previous menu (or measure mode)
- Cancel the changes made in parameter being edited

Symbol used in the manual: [ENTER] Functions:

- Start to edit the parameter
- Enter to the sub-menu,
- Confirmation of changes made in parameter being edited

Symbol used in the manual: [^] [v] Functions:

- Change of the present menu,
- Modification of the parameter value,
- Change of the display mode.


## 6. PRINCIPLE OF OPERATION

After turning the power supply on, device ID and software version are showed on the display, next the controller goes to the measurement mode.

### 6.1. MEASUREMENT MODE

In the measure mode, the measurement results, are displayed on the display. If the result of measurement exceeds the permissible measurement range, warning "-Hi-" or "-Lo-" is displayed rather than calculated result, depends on exceeded value. The warning can be effect of measurement circuit malfunction. In that case "-Lo-" means shortcut and "-Hi-" means break of measurement circuit.

In the measurement mode user can check main thresholds values. After pressing [^^] or [v] button, name of the threshold (e.g. "rEL1") and his value will be displayed on the display in alternating mode. If [^] or [v] will be pressed in 5 sec again, the next threshold will be displayed, else the device comes back to the measurement mode. If a free access is enabled
(see description of "SECu" menu), user can change the value of particular threshold pressing button [ENTER] (see: PARAMETERS EDITION).

All accessible parameters can be changed by entering the menu (see: DEVICE PROGRAMMING). Use the local keyboard or the remote controller to do it. (Note: all parameters can be remote changed via RS-485 interface).

Configuration of the device (via menu or RS 485 interface) do not stops measures.

### 6.2. DETECTION OF THE PEAK VALUES

The PMT-920 controller is equipped with peaks detection function. It can detect a peaks of the input signal and display their values. Presets connected with this function are placed in "HOLd" menu (see description of "HOLd" menu). The detection of the peak can be done if the measured signal raises and drops of value at least equal to parameter "PEA". Detected peaks are displayed during the time defined by parameter "timE". If a new peak will be detected while one is displayed, this new peak will be displayed and display time counter will be cleared (Figure 6.1). If no peaks are detected while time "timE" elapses, device starts to show the current value of input signal again.

The relays/LEDs can be controlled depend on the current value of input signal or the peak value (see "HOLd" menu).


Figure 6.1. Process of peaks detection

### 6.3. CONTROL OF THE RELAY OUTPUTS

The control of the object (measured signal) is realized via relay outputs. Front panel LEDs named „R" indicates the state of particular relay output.

(i)If device is not equipped with one or more relay outputs, menus refer to this relays are available, but apply to LED indicators only. In such case LEDs indicates exceeding of particular thresholds.

Modes of the control can be changed depend on the values of parameters "SEtP", "SEt2", "HYSt", "modE", "t on", "toFF", "unit" and "AL". Depend on "modE" parameter, relays can be not used or controlled over one or two thresholds values.

If one threshold is used (Figure 6.2) the relay can be turned on ("modE" = "on") or off ("modE" = "oFF") when the input signal value is contained in zone A. If two thresholds are used (Figure 6.3) the relay will be turned on when value of input signal is contained in zone $\boldsymbol{A}$ ("modE" = "in") or zone B ("modE" = "out") and turned off if the signal is contained in the second one.


Figure 6.2. One threshold control of the relay/LED outputs


Figure 6.3. Two threshold control of the relay/LED outputs

(i)The relay outputs and LEDs (named R) can be controlled depend on both - the current value and the peak value (when peak detection is active) of the input signal.

### 6.3.1. One threshold mode

Figure 6.4 presents the principle of relay outputs operation for one threshold mode, and an example values of other parameters.
a)


Description:
parameter
A, B, C, D

- points where measured signal exceeds border values (expected value $\pm$ allowed deviation)
$B_{\text {ON }}, B_{\text {OFF }}, D_{\text {ON }}, D_{\text {OFF }}-$ relays state changes moments: (for " $t$ on" $>0$, "toFF" $>0$ )
$\mathbf{t}_{\mathrm{A}}, \mathbf{t}_{\mathbf{B}}, \mathbf{t}_{\mathbf{C}}, \mathbf{t}_{\mathbf{D}} \quad$ - time periods while input signal is in zone $A$ or zone $B$

Figure 6.4. Principle of LED/relay output operation for one threshold mode
Parameter "SEtP" sets a threshold of the relay, and parameter "HYSt" sets a hysteresis of the relay (Figure 6.4 a ). The relay can change his state only when input value exceeds (over or under) border value and $t_{A}, t_{B}, t_{c}, t_{D}$ times (Figure 6.4) are bigger than the time defined by parameters "t on", "toFF" and "unit". Border values means values equal threshold+hysteresis and threshold-hysteresis respectively.

If "t on" and "toFF" parameters are set to "0", then the relay state will be changed as soon as input value exceeds any of the border values (see points $A$ and $C$, Figure 6.4 a, b, c).

If values of "t on" or/and "toFF" are positive, then relay state will be turned on if the input value exceeds the border values and stay bigger (or lower) during at least
"t on" (see points Bon, Don, Figure 6.4 a, d, e). Similarly, the relay will be turned off if time "toFF" elapse since the input signal value exceeds any of the border values (see points Boff, Doff, Figure $6.4 \mathrm{a}, \mathrm{d}, \mathrm{e}$ ).

If $t_{A}, t_{B}, t_{C}$ or $t_{D}$ (when input signal stay in zone $\boldsymbol{A}$ or zone $\boldsymbol{B}$ ) are lower than parameters " t on" or "toFF", the relay will not change his state (see points A and C, Figure 6.4 a, d, e).

The state of relay output while the input value exceeds the border values (points $A, B, C$, D) is described by parameter "modE". The relay can be turned on ("modE" = "on"), or turned off ("modE" = "oFF") when input signal value is contained in zone A (Figure 6.4 a).

The parameter "AL" allow user to set the relay output behaviour in critical situations (e. g. Input values exceeds permissible measurement range). User can select that the relays will be turned on, turned off,or not changed in critical situations.

All parameters connected with relay outputs are described in paragraph "rEL1" menu.

### 6.3.2. Two thresholds mode

a)


Objaśnienie:
A, B, C, D, E - points where measured signal exceeds border values (expected value $\pm$ allowed deviation)
$\mathrm{B}_{\text {on }}, \mathrm{B}_{\text {OFF }}, \mathrm{C}_{\text {on }}, \mathrm{C}_{\text {off }}, \mathrm{E}_{\text {on }}, \mathrm{E}_{\text {OFF }} \quad$ - relays state changes moments: (for "t on" $>0$, "toFF" $>0$ )
$\mathbf{t}_{A}, \mathbf{t}_{\mathrm{B}}, \mathbf{t}_{\mathrm{c}}, \mathbf{t}_{\mathrm{D}}, \mathbf{t}_{\mathrm{E}} \quad-$ time periods while input signal is in zone $A$ or zone $B$
Figure 6.5. Principle of LED/relay output operation for two thresholds mode

Figure 6.5 presents the principle of relay outputs operation for two thresholds mode, and an example values of other parameters. In this mode parameter "SEt2" is accessible in common with "SEtP", this parameter describes a second threshold of the relay output. The parameters "HYSt", "modE", "t on", "toFF", "unit" and "AL" are connected with both "SEtP" and "SEt2" thresholds. While the controlling process, the relay output changes his state depends of both "SEtP" and "SEt2" thresholds in similar way as it was described in one threshold mode.

If two threshold mode is used, "modE" parameter defines state of the relay output when the input value occurs in a particular zone defined by border values of both thresholds. The relay can be turned on if the input value is contained in zone A ("modE" = "in") or zone B ("modE" = "out") and turned off if it is contained in the second one (Figure 6.5).

(i)
The sequence of thresholds "SEtP" and "SEt2" can be set in any order, due to the control of relay outputs is done depend on difference between thresholds values (zone A ) and outside of threshold values (zone B).

## 7. DEVICE PROGRAMMING

The device menu allow user to set all parameters connected to operation of measurement input, control modes, critical situations behaviour, communication via RS-485 and access settings. The meaning of the particular parameters is described in paragraph MENU DESCRIPTION.

Some of the parameters can be accessed without menu entering (quick view mode). After pressing [^] or [v] button, name of the threshold (e.g."rEL1") and his value will be displayed on the display in alternating mode. If [^] or [v] will be pressed in 5 sec again, the next threshold will be displayed, else the device comes back to the measurement mode. If a free access is enabled (see description of "SECu" menu), user can change the value of particular threshold pressing button [ENTER] (see: PARAMETERS EDITION).

(i)If particular parameter has been changed and confirmed in quick view mode, its new value is displayed in alternating mode with parameter name by few seconds. Confirmed changes may be checked or user can switch viewed parameter pressing [^] or [v] button.

### 7.1. PROGRAMMING MENU

To enter main menu (being in the measurement mode) operator must to press and hold at least 2 sec . [ESC/MENU] button.

If the user password is defined (see parameter "Scod", menu "SECU"), operator have to enter correct one before proceeding to menu options. Entering of the passwords is similar to the edition of numeric parameters (see: PARAMETERS EDITION ), however presently editing digit is showed only on the display, other digits are replaced by "-" sign.

After entering of last digit of the password first menu position will be displayed (if the password is correct) or warning "Err" in other case.


Pay attention when device parameters are being changed. If it is possible, turn off controlled installation (machine).

## Functions of the buttons while sub-menu and parameters choice:

[ESC/MENU] button allow user to exit present menu level and goes to upper level menu (or measurement mode).

After about 1 min. since last use of the buttons, device exits the menu mode and returns to the measurement mode (only if no parameters are in editing mode).

### 7.2. PARAMETERS EDITION

To start edition of any parameter user should select name of desired one using [^] [v] buttons and then press [ENTER].

### 7.2.1. Numeric parameters (digit change mode)

Numerical parameters are displayed as decimal numbers. The mode of its new value entering depends on chosen edit method ( see parameter „Edit").

In mode "by digit" („Edit"="dig") pressing one of the keys [^] or [v] causes change of current position (flashing digit) or the sign (+/-). Short pressing of the [ENTER] button causes change of the position (digit).

Press [ENTER] at least 2 seconds to accept the changes, after that question "SEt?" is displayed, and user must to confirm (or cancel) the changes. To conform changes (and story it in EEPROM) press [ENTER] button shortly after "SEt?" is displayed. To cancel the changes press [ESC] button shortly after "SEt?" is displayed. After that device returns to the menu.

### 7.2.2. Numeric parameters (slide change mode)

In "slide change" mode („Edit"="Slid"), buttons [^^] and [v] has different functions.
To increase edited value press (or press and hold) [^] button only, the increasing became quickest as long as button [^^] is pressed. To slow down the increasing, button [v] can be used. If [ v ] is pressed shortly (and button [^^] is still pressed), increasing slow down for a moment only, if [ $\mathbf{v}$ ] is pressed and held while button [^] is still pressed the increasing slow down and will be kept on lower speed.

To decrease edited value press (or press and hold ) [v] button only. The decreasing became quickest as long as button [v] is pressed. To slow down the decreasing, button [^] can be used. If [ ${ }^{\wedge}$ ] is pressed shortly (and button [ $\mathbf{v}$ ] is still pressed), decreasing slow down for a moment only, if [^${ }^{\wedge}$ ] is pressed and held while button [ $\mathbf{v}$ ] is still pressed the decreasing slow
down and will be kept on lower speed.
Press [ENTER] at least 2 seconds to accept the changes, after that question "Set?" is displayed, and user must to confirm (or cancel) the changes. To conform changes (and story it in EEPROM) press [ENTER] button shortly after "SEt?" is displayed. To cancel the changes press [ESC] button shortly after "SEt?" is displayed. After that device returns to the menu.

### 7.2.3. Switch parameters ("LIST" type)

Switch parameters can be described as a sets of values (a lists) out of which only one of the options available on the list can be selected for the given parameter. Options of switching parameter are selected using [^^], [v] keys.

Short pressing of [ENTER] causes in displaying of the acknowledge question ("SEt?"). If key [ENTER] is pressed again, the changes are accepted, stored in EEPROM end the edition process finished. Pressing the key [ESC] after "SEt?" causes in cancelling of made changes and returning to menu.

## Functions of buttons when editing numeric and switching parameters:



While editing numeric parameter:

- change of current (flashing) digit
- slide change of value (acceleration, deceleration, direction change)

While editing switch parameter - selection of switch parameter.
If numerical parameter is being edited, a short press of [ENTER] button change edited position. A long press of [ENTER] button (at lest 2 sec.) causes of display a "SEt?" ask, which allow user to make sure if change of the parameter value is correct. If switch parameter is being edited, a short press of [ENTER] button causes of display a "SEt?" ask. When [ENTER] button is pressed again (while "SEt?" is displayed) the new value of the parameter is stored in EEPROM memory.

Pressing this button operator can cancel the changes done up to now (if they were not approved by [ENTER] button after the "SEt?" ask) and come back to menu

### 7.3. MENU DESCRIPTION

"- - - "

- password checking. If some password different from „0000" is set, then every enter to main menu follows the entering of password. If entered password is correct then first menu position will be displayed else warning "Err", and unit returns to measurement mode.

Due to problem with direct displaying of " $m$ " letter, it is exchanged with special sign " $\bar{\pi}$ ". Independently in user manual letter " $\mathbf{m}$ " is used to make it more readable (example: "modE").

### 7.3.1. "rEL1" menu

This menu allows to configure the operation mode of relays and LEDs marked „R" (e.g. „R1").
If there are few relay outputs available, then every output has its own configuration menu (e.g. menu „rEL2" for relay (LED) „R2"). Principle of the relays operation is described in paragraph CONTROL OF THE RELAY OUTPUTS.

- The relay outputs and LEDs (named $\mathbf{R}$ ) can be controlled depend on both - the current value and the peak value (when peak detection is active) of the input signal.
- If device is not equipped with one or more relay outputs, menus refer to this relays are available, but apply to LED indicators only. In such case LEDs indicates exceeding of particular thresholds.
"SEtP" - first threshold of the relay (range -999 $\div 9999$ ). Negative values can be input by selecting a "-" sign on first digit (to change value use [^] and [v] buttons). Threshold is the medium value of relay hysteresis.
"SEt2" - second threshold of the relay (range -999 $\div 9999$ ). Negative values can be input by selecting a "-" sign on first digit ( to change value use [^] and [v] buttons). This threshold is accessible when "modE" parameter is set to „in" or „out" value. Threshold is the medium value of relay hysteresis.
"HYSt" - hysteresis of relay (range $0 \div 999$ ). Full hysteresis of the relay is equal to $2 x$ "HYSt" parameter. The relay state can change when an input signal is out of threshold-hysteresis to threshold+hysteresis zone.

(i)Presented parameters should be set to ensure that "SEtP" + "HYSt", "SEt2" + "HYSt", "SEtP" - "HYSt" or "SEt2" - "HYSt" do not exceeds the measure range. Additionally, in two threshold mode ("modE"= „in" or „out"), the hysteresis for both thresholds must not cover each other (in other case relay can't change his state).
"modE" - relay operation mode:

$$
\begin{array}{ll}
\text { "noAC" } & \text { - the relay is not active (permanent turned off) } \\
\text { "on" } & \text { one threshold mode, the relay is turned ON when input signal exceeds } \\
& \text { SEtP + HYSt value, and is turned off back when the input signal became } \\
\text { lower than SEtP - HYSt, }
\end{array}
$$

"out" - two threshold mode, relay is turned ON when the input value is bigger than "bigger threshold + HYSt" and lower than "lower threshold HYSt", and turned on when the input signal is contained in the second zone. The bigger threshold means bigger one of "SEtP" and "SEt2" thresholds, the lower threshold" means lower one of "SEtP" and "SEt2" thresholds.
"modb" - the relay is controlled via RS-485 interface, independently on the input signal.

- LEDs light when relays are closed, independently of relays' mode.
- When power supply fail, unit do not store relays state selected by RS-485 interface.
"t on" - turn on delay time, the relay is turned on with delay equal "t on" if the input value exceeds appropriate border value (defined with threshold and hysteresis), at least " $t$ on" time. "t on" range $0 \div 99.9$, defined with 0.1 sec . resolution. Unit of this parameter is set by "unit" parameter.
"toFF" - turn off delay time, the relay is turned off with delay equal "toFF" if the input value exceeds appropriate border value (defined with threshold and hysteresis), at least "toFF" time. "toFF" range $0 \div 99.9$, defined with 0.1 sec . resolution. Unit of this parameter is set by "unit" parameter.

If time when the input signal exceeds some border value is shorter than "t on" or "toFF" time, the relay do not change his state (see paragraph: CONTROL OF THE RELAY OUTPUTS).
"unit" - unit of time for "t on" i "toFF" parameters. Can be set on one of two values:
"min" - minutes,
"SEC" - seconds.
"AL" - this parameter defines the relay reaction when some critical situations occurs:
"noCH" - relay do not change his state,
"on" - relay will be turned on,
"oFF" - relay will be turned off.
If parameter "modE" is set to "on" , "oFF", "in" or "Out" the "critical situation" means that allowable measurement range is exceeded.
If parameter "modE" is set to "modb", the "critical situation" means communication delay (when no data is received) longer than "mbtO" parameter (see description: "rS" menu).

- If option "noCH" is selected for "AL" parameter, behaviour of the relay may depend on "FiLt" parameter in some cases. If "FiLt" is set to big value and the input signal drops, result value of the measure will change slow, causes of turning on or off relay due to thresholds values. The critical situation is slowly
detected, so it is impossible to predict the relay state in that situations.
- If parameter „AL" = „on", the relay will be turned on in the critical situations, even if his parameter "modE" = "noAC".


### 7.3.2. "inPt" menu

This menu presets the measurement input:
"tYPE" - type of the input / sensor. This parameter can be set to values:
"Pt 1" - Pt-100 input,
"Pt 5" - Pt-500 input,
"Pt10" - Pt-1000 input.
"FiLt" - this parameter sets filtration rate. It can be set to values from 0 (no filtration ) to 5 (strongest filtration - time window about 2 sec ).
"toFS" - offset (expressed in $0.1^{\circ} \mathrm{C}$, range $\pm 9.9^{\circ} \mathrm{C}$.). This parameter allows shifting of measurement scale, and express value added to calculated (measured) result.

### 7.3.3. "bri" parameter

This parameter allows user to set bright of the LED display, bright can be set to conventional values from 1 to 8.

### 7.3.4. "CoL" menu

This menu contains settings related to signalisation via display colour. This kind of signalisation consist in change of display colour (from basic colour to „active" colour) in defined situations, for example after change of R1 state.
"SCoL" - basic colour ( the second one becomes „active" colour):
"grEE" - main colour is green,
"rEd" - main colour is red.
"C r1","C r2" - control the display colour according to relay (R1, R2 separate )state :
"oFF" - control for particular relay is off,
"on" - control for selected relay is on, the display will change its colour after selected relay becomes active.
"C AL" - control the display colour according to alarm situations :
"oFF" - control is off,
"on" - control is on, the display will change its colour after alarm situation occurs.
"C Pr" - this setting enables additional threshold for display colour controlling, detailed conditions of this control are defined by „dir", „SEtP" and „HySt" parameters of "CoL" submenu.
"oFF" - no additional threshold.
"on" - additional threshold enabled, the display will change its colour after result satisfy conditions defined by "dir", „SEtP" and "HySt" parameters of "CoL" submenu.
"dir" - this parameter defines the direction of result changes activating change of display colour:
"morE" - display will change its colour after the result is higher than threshold +hysteresis
"LESS" - display will change its colour after the result is lower than threshold + hysteresis

```
"SEtP" - additional threshold value (range -999 \(\div 9999\) ). Negative values can be input by selecting a "-" sign on first digit ( to change value use [^^] and [v] buttons). Threshold is the medium value of relay hysteresis.
```

"HYSt" - Hysteresis of colour indication (range $0 \div 999$ ). Full hysteresis is equal to $2 x$ "HYSt" parameter. The display colour can change when an input signal is out of threshold-hysteresis to threshold+hysteresis zone.

- Presented parameters should be set to ensure that "SEtP" + "HYSt" and "SEtP" - "HYSt" do not exceeds the measure range.
"CrES" - permission to use any local key to acknowledgement of display colour change. Acknowledgement causes clear of all events generating display colour changes (to active colour), and restores basic colour of the display.
"oFF" - acknowledgement disabled,
"on" - acknowledgement enabled.


### 7.3.5. 'HOLd" menu

This menu contains parameters connected with peak detection function. See also full description of the peak detection function in paragraph: DETECTION OF THE PEAK VALUES
"modE" - the type of detected changes of the input signal, can be set to values:
"norm" - peaks, peak and next drop of the input signal of value equal at least "PEA",
"inv" - drops, drop and next peak of the input signal of value equal at least "PEA",
"PEA" - minimal detected signal change classified as peak or drop (see Figure 6.1)
"timE" - maximum time of displaying of the peak (drop) value, can be set from 0.1 to 19.9 sec , with 0.1 sec . resolution
"HdiS" - type of displayed values:
"rEAL" - current value is displayed,
"HOLd" - peak (drop) value is displayed,
"H r1", "H r2" - relay/LED outputs (R1, R2) operation mode:
"rEAL" - relay/LED operates depend on the current value, "HOLd" - relay/LED operates depend on the peak (drop) value.

### 7.3.6. 'SECu" menu

This menu contains presets connected with availability of other parameters:
"Scod" - user password (4-digits number). If this parameter is set at value " 0000 ", user password is turned off.

If the user do not remember his password, the access to the menu is possible by the "one-use password". To get this password please contact with Marketing Division. "Single use password" can be used only one time, after that it is destroyed. Entering this password causes in clearing of user password, it means sets the user password to „0000".

(i)The "one-use password" can be used ONE TIME ONLY, it is impossible to use it again! The "one-use password" can be restored by Service Division only.
"A r1, A r2" - this option permits user ("on") or prohibits ("oFF") to modify the thresholds of the relays/LEDs R1, R2 without knowledge about user password.

### 7.3.7. "rS" menu

This menu is connected with RS-485 interface, and sets his properties:
"Addr" - this parameter defines the address of the device, accordingly to Modbus protocol. It can be set in range from 0 to 199. If the value 0 is set then device, responds to frames with address 255 (FFh).
"bAud" - this parameter determines RS-485 interface baud rate. It can be set to one of 8 possible values: "1.2", "2.4", "4.8", "9.6", "19.2", "38.4","57.6","115.2", which respond to the baud rates of $1200,2400,4800,9600,19200,38400,57600$ and 115200 bit/s respectively.
"mbAc" - this parameter sets the access to the configuration registers of the device. Possible values:
"on" - configuration registers can be set via RS-485 interface,
"oFF" - configuration registers can not be set via RS-485 interface. The access to registers no 04h i 05h cant be denied by "mbAc" parameter (see: LIST OF REGISTERS).

| "mbtO" | - this parameter defines maximal time (sec) between following frames received by |
| :--- | :--- |
| the device. If the delay will be greater than the value of "mbt"" parameter, the |  |
| relays which are controlled via RS-485 interface, will set to alert state (see "rEL1" |  |
| menu description). Parameter "mbtO" can be set to values from 0 to 99 seconds. |  |
| The value 0 means that the time will be not controlled. |  |

"Std" - answer as quick as possible, no additional delay
"10c"
" 20c"
" 50 c"
"100c"
"200c"

- answer delayed of $10,20,50,100$ of 200 chars respectively, where one character time depends on selected baud rate
(i) In the most cases parameter "rESP" should be set to "Std" (no additional delay). Unfortunately for some third party RS-converters "rESP" should be adjusted experimentally. Table 7.1 contains most frequently used values.

| "bAud" parameter | "38.4" | "57.6" | "115.2" |
| :---: | :---: | :---: | :---: |
| "rESP" parameter | " $10 \mathrm{c} "$ | " $20 \mathrm{c} "$ | " $50 \mathrm{c} "$ |

Tab.7.1. Settings of "rESP" parameter

### 7.3.8. "Edit" parameter

This parameter allows to change the edition mode of numerical parameters:
"dig" - the change to "by digit" mode,
"Slid" - slide change mode.

### 7.3.9. "dEFS" parameter

This setting allows to restore the factory settings of the device. To get the access to this option special password is required: „5465", next the device displays acknowledge question „SEt?". Press [ENTER] to acknowledge the restoring of factory settings or [ESC] to cancel.

### 7.3.10. "SErv" menu

This menu contains the parameters for authorized service only. To enter this menu proper service password must be entered. Improper settings can causes of damage of the device.

### 7.4. MENU STRUCTURE




## 8. THE ALARM LED

Alarm LED (AL) lights in cases:

- exceeding of permissible measurement range
- detection of sensor malfunction (shortcut or break of measurement circuit)


## 9. THE MODBUS PROTOCOL HANDLING

Transmission parameters: 1 start bit, 8 data bits, 1 or 2 stop bit ( 2 bits are send, 1 and 2 bits are accepted when receive), no parity control
Baud rate: selectable from: 1200 to 115200 bits/second
Transmission protocol:
MODBUS RTU compatible
The device parameters and display value are available via RS-485 interface, as HOLDINGtype registers (numeric values are given in U2 code) of Modbus RTU protocol. The registers (or groups of the registers) can be read by 03h function, and wrote by 06h (single registers) or 10h (group of the registers) accordingly to Modbus RTU specification. Maximum group size for 03h and 10h functions can not exceeds 16 registers (for single frame).

(i)The device interprets the broadcast messages, but then do not sends the answers.

### 9.1. LIST OF REGISTERS

| Register | Write | Range | Register description |
| :---: | :---: | :---: | :---: |
| 01h | No | -999 $\div 6000$ | Measurement value (no decimal point) |
| 02h | No | Oh, A0h, 60h | The status of the current measurement; $\mathbf{O h}$ - data valid; $\mathbf{A O h}$ - top border of the measurement range is exceeded; $\mathbf{6 0 h}$ - bottom border of the measurement range is exceeded; |
| 03h | No | 1 | Decimal point position, constant value: 1 - " 0.0"; |
| 04h | Yes | see descr. | State of the relays and alarm LED (binary format) <br> ( 1 - on, 0 - off): $00000000000 \mathrm{e00ba}$ <br> a - relay R1; b - relay R2; e - alarm LED; <br> If written, only $\mathbf{a}, \mathbf{b}$ bits are important (others are ignored) these bits allows user to control the relays via RS-485 interface |
| 06h | No | -999 $\div 6000$ | Peak (drop) value (no decimal point) |
| 10h | Yes | $0 \div 2$ | "tyPE" parameter in "InPt" menu (input type). $\text { 0-Pt-100; } 1 \text {-Pt-500; } 2 \text {-Pt-1000 }$ |
| 12h | Yes | $0 \div 5$ | "FiLt" parameter in "InPt" menu (measurement filtering rate) |


| Register | Write | Range | Register description |
| :---: | :---: | :---: | :---: |
| 18h | Yes | -99 $\div 99$ | "toFS" parameter in "InPt" menu (shift of measurement scale), expressed by $0,1^{\circ} \mathrm{C}$ |
| $20{ }^{2}$ | Yes | $0 \div 199$ | Device address |
| 21h | No | 20B7h | Device identification code (ID) |
| $22 h^{3}$ | Yes | $0 \div 7$ | "bAud" parameter in "rS" menu (baud rate); <br> 0-1200 baud; 1-2400 baud; 2-4800 baud; 3-9600 baud; <br> 4-19200 baud; 5-38400 baud; 6-57600 baud; 7-115200 baud |
| $23 h^{4}$ | Yes | $0 \div 1$ | "mbAc" parameter in "rS" menu (permission to write registers via RS-485 interface); $\mathbf{0}$ - write denied ; $\mathbf{1}$ - write allowed |
| 24h | Yes | see descr. | Parameters of "SECU" menu (binary format (0-„oFF", 1 - „on"): bit 0 - "A r1" parameter; bit 1 - "A r2" parameter <br> bit 2 - "A r3" parameter; bit 3 - "A r4" parameter |
| 25h | Yes | $0 \div 5$ | "rESP" parameter in "rS" menu (additional response delay); 0 - no additional delay; 1 - "10c" option; 2-"20c" option; 3 - "50c" option; 4 - "100c" option; 5 - "200c" option; |
| 27h | Yes | $0 \div 99$ | "mbtO" parameter in "rS" menu (maximum delay between received frames); 0 - no delay checking; <br> $1 \div 99$ - maximum delay expressed in seconds |
| 2Dh | Yes | $1 \div 8$ | "bri" parameter (display brightness); <br> 1 - the lowest brightness; 8 - the highest brightness |
| 2Eh | Yes | $0 \div 1$ | "SCoL" parameter in "CoL" menu (main colour of display); 0 - green; 1 - red |
| 2Fh | Yes | $0 \div 1$ | "Edit" parameter (numerical parameters edit mode); 0- „dig" mode; 1 - „SLid" mode |
| 30h | Yes | -999 $\div 9999$ | "SEtP" parameter in "rEL1" menu, no decimal point included |
| 31h | Yes | -999 $\div 999$ | "HySt" parameter in "rEL1" menu, no decimal point included |
| 32h | Yes | $0 \div 3$ | "modE" parameter in "rEL1" menu: <br> 0 - "noAC" mode; 1 - "on" mode; 2 - "oFF" mode; $\mathbf{3}$ - "in" mode; <br> 4 - "out" mode; 5 - "modb" mode |
| 33h | Yes | $0 \div 999$ | "t on" parameter in "rEL1" menu, expressed in tenth of seconds or tenth of minutes depend on "unit" parameter - register no. 35h) |
| 34h | Yes | $0 \div 999$ | "toFF" parameter in "rEL1" menu, expressed in tenth of seconds or tenth of minutes depend on "unit" parameter - register no. 35h) |
| 35h | Yes | $0 \div 1$ | "unit" parameter in "rEL1" menu: 0 - seconds; 1 - minutes |
| 36h | Yes | $0 \div 2$ | "AL" parameter in "rEL1" menu: $\mathbf{0}$ - no changes; $\mathbf{1}$ - on; $\mathbf{2 - o f f}$ |
| 37h | Yes | $-999 \div 9999$ | "SEt2" parameter in "rEL2" menu, no decimal point included |
| 38h | Yes | -999 $\div 9999$ | "SEtP" parameter in "rEL2" menu, no decimal point included |
| 39h | Yes | -999 $\div 999$ | "HySt" parameter in "rEL2" menu, no decimal point included |
| 3Ah | Yes | $0 \div 3$ | "modE" parameter in "rEL2" menu: <br> 0 - "noAC" mode; 1 - "on" mode; 2 - "oFF" mode; 3 - "in" mode; <br> 4 - "out" mode; 5 - "modb" mode |


| Register | Write | Range | Register description |
| :---: | :---: | :---: | :---: |
| 3Bh | Yes | $0 \div 999$ | "t on" parameter in "rEL2" menu, expressed in tenth of seconds or tenth of minutes depend on "unit" parameter - register no. 3Dh) |
| 3Ch | Yes | $0 \div 999$ | "toFF" parameter in "rEL2" menu, expressed in tenth of seconds or tenth of minutes depend on "unit" parameter - register no. 3Dh) |
| 3Dh | Yes | $0 \div 1$ | "unit" parameter in "rEL2" menu: 0 - seconds; 1 - minutes |
| 3Eh | Yes | $0 \div 2$ | "AL" parameter in "rEL2" menu: $\mathbf{0}$ - no changes; $\mathbf{1}$ - on; $\mathbf{2}$ - off |
| 3Fh | Yes | -999 $\div 9999$ | "SEt2" parameter in "rEL2" menu, no decimal point included |
| 50h | Yes | $0 \div 1$ | "modE" parameter in "HOLd" menu (type of detected changes): 0 - peaks; 1 -drops |
| 51h | Yes | $0 \div 9999$ | "PEA" parameter in "HOLd" menu (minimum detectable change, no decimal point included) |
| 52h | Yes | $1 \div 199$ | "timE" parameter in "HOLd" menu, maximum peaks' (or drops') display time expressed in seconds |
| 53h | Yes | $0 \div 1$ | "HdiS" parameter in "HOLd" menu: 0 - "rEAL" mode ; 1 - "HOLd" mode |
| 54h | Yes | $0 \div 1$ | "H r1" parameter in "HOLd" menu : 0 - "rEAL" mode ; 1-"HOLd" mode |
| 55h | Yes | $0 \div 1$ | "H r2" parameter in "HOLd" menu: 0 - "rEAL" mode ; 1 - "HOLd" mode |
| 60h | Yes | see descr. | Parameters of "CoL" menu (binary format, 0-„oFF", 1 - „on"): <br> bit 7 - "C AL" parameter; <br> bit 6 - "C Pr" parameter; <br> bit 1 - "C r2" parameter; <br> bit 0 - "C r1" parameter. |
| 61h | Yes | $0 \div 1$ | "CrES" parameter in "CoL" menu (reset of colour indication): 0-„oFF"; 1 - „on" |
| 62h | Yes | $0 \div 1$ | "dir" parameter in "CoL" menu (direction of value changes): 0 - „morE"; 1 - „LESS" |
| 63h | Yes | -999 $\div 9999$ | "SEtP" parameter in "CoL" menu, no decimal point included |
| 64h | Yes | -999 $\div 999$ | "HySt" parameter in "CoL" menu, no decimal point included |

2 - after writing to register no 20 h the device responds with an "old" address in the message.
3 - after writing to register no 22h the device responds with the new baud rate.
4 - the value of the "mbAc" parameter is also connected to write to this register, so it is possible to block a writes, but impossible to unblock writes via RS-485 interface, The unblocking of the writes is possible from menu level only.

### 9.2. TRANSMISSION ERRORS DESCRIPTION

If an error occurs while write or read of single register, then the device sends an error code according to Modbus RTU specifications (example message no 1).

Error codes:
01h - illegal function (only functions 03h, 06h and 10h are available),
02h - illegal register address
03h - illegal data value
08h - no write permission ( see: "mbAc" parameter)
A0h - exceed of upper border of input range
60h - exceed of lower border of input range
A0h and 60h codes can appear only during reg. 01h is reading by 03h function (read of a single register).

### 9.3. EXAMPLES OF QUERY/ANSWER FRAMES

Examples apply for device with address 1 . All values are represent hexadecimal.
Field description:
ADDR Device address on modbus network
FUNC Function code
REG H,L Starting address (address of first register to read/write, Hi and Lo byte)
COUNT H,L No. of registers to read/write (Hi and Lo byte)
BYTE C Data byte count in answer frame
DATA H,L Data byte (Hi and Lo byte)
CRC L,H CRC error check (Hi and Lo byte)

1. Read of the displayed value (measurement), PMT-920 device address $=01 \mathrm{~h}$ :

| ADDR | FUNC | REG H,L |  | COUNT H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 03 | 00 | 01 | 00 | 01 | D5 | CA |

a) The answer (we assume that the measure result is not out of range):

| ADDR | FUNC | BYTE C | DATA H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 03 | 02 | 00 | FF | F8 | 04 |

DATA H, L - displayed value $=255$, no decimal point.
Decimal point position can be read from reg. 03h.
b) The answer (if an error occur):

| ADDR | FUNC | ERROR | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: |
| 01 | 83 | 60 | 41 | 18 |

ERROR - error code $=60 \mathrm{~h}$, bottom border of the measurement range is exceeded

## 2. Read of device ID code

| ADDR | FUNC | REG H,L |  | COUNT H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 03 | 00 | 21 | 00 | 01 | D4 | 00 |

The answer:

| ADDR | FUNC | BYTE C | DATA H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 03 | 02 | 20 | B7 | E1 | F2 |

DATA - identification code (20B7h)
3. Change of the device address from 1 to 2 (write to reg. 20h)

| ADDR | FUNC | REG H,L |  | DATA H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 06 | 00 | 20 | 00 | 02 | 09 | C1 |

DATA H-0
DATA L - new device address (2)
The answer (the same as the message):

| ADDR | FUNC | REG H,L |  | DATA H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 06 | 00 | 20 | 00 | 02 | 09 | C1 |

4. Change of baud rate of all devices connected to the net (BROADCAST message).

| ADDR | FUNC | REG H,L |  | COUNT H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00 | 06 | 00 | 22 | 00 | 04 | 29 | D2 |

DATA H-0
DATA L-4, new baud rate 19200 baud

(i)Device do not reply to BROADCAST-type messages.
5. Read of the registers 1 , 2 and 3 in one message (example of reading a number of registries in one frame):

| ADDR | FUNC | REG H,L |  | COUNT H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 03 | 00 | 01 | 00 | 03 | 54 | $0 B$ |

COUNT L - the count of being read registers (max.16)
The answer:

| ADDR | FUNC | BYTE C | DATA H1,L1 |  | DATA H2,L2 |  | DATA H3,L3 |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 03 | 06 | 00 | 0 A | 00 | 00 | 00 | 01 | 78 | B4 |

DATA H1, L1 - reg. 01h (10 - displayed value "1.0"),
DATA H2, L2 - reg. 02h (0 - no errors),,
DATA H3, L3 - reg. 03h (1-decimal point position " 0.0").
(i)

There is no full implementation of the Modbus Protocol in the device. The functions presented above are available only.

## 10. DEFAULT AND USER'S SETTINGS LIST

| Parameter | Description | Default value | User's value | Desc. page |
| :---: | :---: | :---: | :---: | :---: |
| Parameters of relay R1 operation ("rEL1" menu) |  |  |  |  |
| SEtP | Relay R1 threshold | 20.0 |  | 22 |
| SEt2 | Relay R1 second threshold | 30.0 |  | 22 |
| HYSt | Hysteresis of relay R1 | 0.0 |  | 22 |
| modE | Operation mode of relay R1 | in |  | 22 |
| $t$ on | Turn on delay of relay R1 | 0.0 |  | 23 |
| toFF | Turn off delay of relay R1 | 0.0 |  | 23 |
| unit | Unit of "t on", "toFF" parameters of relay R1 | SEC |  | 23 |
| AL | Reaction for critical situation of relay R1 | oFF |  | 23 |
| Parameters of relay R2 operation ("rEL2" menu) |  |  |  |  |
| SEtP | Relay R2 threshold | 40.0 |  | 22 |
| SEt2 | Relay R2 second threshold | 50.0 |  | 22 |
| HYSt | Hysteresis of relay R2 | 0.0 |  | 22 |
| modE | Operation mode of relay R2 | in |  | 22 |
| $t$ on | Turn on delay of relay R2 | 0.0 |  | 23 |
| toFF | Turn off delay of relay R2 | 0.0 |  | 23 |
| unit | Unit of "t on", "toFF" parameters of relay R2 | SEC |  | 23 |
| AL | Reaction for critical situation of relay R2 | oFF |  | 23 |
| Configuration of measurement input ("inPt" menu) |  |  |  |  |
| tYPE | Input type | „Pt 1" |  | 24 |
| FiLt | Filtering ratio | 0 |  | 24 |
| toFS | Shifting of measurement scale | 0.0 |  | 24 |
| Display parameters |  |  |  |  |
| bri | Display brightness | bri6 |  | 24 |
| Signalization via colour of the display ("CoL" menu ) |  |  |  |  |
| SCoL | Basic colour of the display | grEE |  | 24 |
| Cr1 | Change display colour after R1 is activated | oFF |  | 24 |
| Cr2 | Change display colour after R2 is activated | oFF |  | 24 |
| C AL | Change display colour after alarm occurs | oFF |  | 24 |
| C Pr | Enable additional threshold while signalisation via colour | oFF |  | 25 |
| dir | The direction of result changes activating change of display colour | morE |  | 25 |


| Parameter | Description | Default value | User's value | Desc. page |
| :---: | :---: | :---: | :---: | :---: |
| SEtP | Threshold of display colour control | 500 |  | 25 |
| HySt | Hysteresis of display colour control | 0 |  | 25 |
| CrES | Enable the use of local keyboard for acknowledgement of display colour signalisation. | oFF |  | 25 |
| Configuration of peaks detection function ("HOLd" menu) |  |  |  |  |
| modE | Kind of detected changes | norm |  | 25 |
| PEA | Minimum detected change | 0.0 |  | 25 |
| timE | Maximum time of peak displaying | 0.0 |  | 25 |
| HdiS | The type of displayed value | HOLd |  | 26 |
| H r1 | Source of relay R1, and LED R1 control | rEAL |  | 26 |
| H r2 | Source of relay R2, and LED R2 control | rEAL |  | 26 |
| Settings of access to the configuration parameters ("SECu" menu) |  |  |  |  |
| A r1 | Permission to changes of relay R1 threshold without of the user password knowledge | on |  | 26 |
| A r2 | Permission to changes of relay R2 threshold without of the user password knowledge | on |  | 26 |
| RS 485 interface configuration (menu "rS") |  |  |  |  |
| Addr | Device address | 0 |  | 26 |
| bAud | Baud rate | 9.6 |  | 26 |
| mbAc | Permission to changes of configuration registers | on |  | 26 |
| mbtO | Maximum delay between received messages | 0 |  | 27 |
| rESP | Additional delay of answer transmission | Std |  | 27 |
| Configuration of numerical parameters edition |  |  |  |  |
| Edit | Numerical parameters edit mode | dig |  | 27 |

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[^0]:    - In order to minimize fire or electric shock hazard, the unit must be protected against atmospheric precipitation and excessive humidity.
    - Do not use the unit in areas threatened with excessive shocks, vibrations, dust, humidity, corrosive gasses and oils.

